Transfer System

Transfer Case Assembly

TCCM EST Circuit diagram (1)

WD-2



Transfer Case Assembly

ATT(or TOD) Circuit diagram (2)



BMAD350A

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BMAD340A

EST (ELECTRONIC SHIFT TRANSFER) INTRODUCTION

EXT system is a kind of part time 4 wheel drive system and its full name is "Electronic shift transfer". Instead of previous free wheel hub, FRRD (Free Running Differential) was adopted and this one is for SOTF (shift on the fly) while vehicle driving. When the vehicle runs with 2WD again, the front axle will be rotated idly due to the vehicle speed and thismakes the noise and vibration on the propeller shaft and ring gear set. Therefore FRRD will prevent these phenomena to get a driving stability, efficiency and improved NVH.

When 4WD is selected by driver, a FRRD air pump motor operates and a dog clutch in FRRD is engaged to pinion shaft making s front wheels drive. Therefore the front propeller shaft and the front drive shaft are coupled rotating together. Oppositely, if 2WD is selected by a driver, the dog clutch in a FRRD is disengaged resulting in disconnection between the front propeller shaft and the front drive shaft.



BKAE090A

Transfer System

TOD (TORQUE ON DEMAND) OR ATT (ACTIVE TORQUE TRANSFER)

INTRODUCTION

TOD system is a kind of full time 4 wheel drive system and its full name is "Torque on demand". The optimum engine torque distribution ration between front and rear is controlled by TOD transfer case. This transfer case is controlled and operated by independent control module, that is TCCM (Transfer case control module) and it is located under the crash padon passenger side.



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The torque transmission ratio to front and rear side is not fixed and it is changed and controlled continuously depends on the road and vehicle driving condition.

Basically the torque split ratio will be 0:100 (that is "FR" situation) on road driving with low and medium vehicle speed. If there is any amount of slip on the rear wheel, the optimum amount of torque will be distributed to front wheel to get a stable driving performance.

The range of torque split ratio is from 0:100 to 50:50. It means the maximum torque amount of front wheel cannot be higher than rear wheel in any kind of road or vehicle condition.

Transfer Case Assembly

According to the speed signal of front and rear wheel from each sensor, the engine torque information from engine ECM, EMC (Electro magnetic clutch) will be activated and it will result the change of depressing force to the multiple disc clutch. If the force is high, more engine torque will be transmitted to front wheel.

Oppositely, if it becomes low, the torque to front side also will be decreased. It means the slip inside of multiple disc clutch will be increased also. Therefore the oil pump for lubrication of clutch is installed and very important for the overall system durability.



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Transfer System

SYSTEM DIAGRAM ACTIVE TORQUE TRANSFER (ATT)



BMAD195A

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Transfer Case Assembly

ELECTRIC SHIFT TRANSFER

1. If a malfunction occurs, the 4WD indicator lamp will blink to warn the driver.



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- 2. Following items will be indicated
 - 1) TCCM
 - 2) Shift motor
 - 3) Magnetic synchronizer clutch
 - 4) Speed sensor
 - 5) Hub solenoid
 - 6) Selector switch
 - 7) Motor position sensor
- 3. DTC Table

5. Meaning of code

- 0 : Lamp ON for 0.5 second
 - 1: Lamp ON for 1 second
- 6. EX) TCCM Fault (DTC: 001)
 - 1) Indicator lamp check (0.6S)
 - 2) Lamp OFF (3S)
 - 3) Lamp ON (0.5S)
 - 4) Lamp OFF (0.5S)
 - 5) Lamp ON (0.5S)
 - 6) Lamp OFF (0.5S)
 - 7) Lamp ON (1S)
 - 8) Lamp OFF (3S)
 - 9) Repeat steps 3) 8).

READING METHOD

- Code Lu ofu فودر Itemامانه 001 TCCM 010 Shift motor 011 Synchronizer clutch 100 Speed sensor 101 Hub solenoid 110 Selector switch 111 Motor position sensor
- 4. DTC Indication
 - 1) Indicator lamp check (0.6S)
 - 2) Lamp OFF (3S)
 - 3) DTC Indication
 - 4) OFF (3S)
 - 5) Repeat steps 3), 4)
 - 6) Repeat steps 3), 4), 5) for additional faults.

Normal

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Transfer System



Fault

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LMAC210C

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Transfer Case Assembly

DTC PATTERN



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Transfer System

ACTIVE TORQUE TRANSFER (TOD)

DTC	Content			
P1725	TOD CONTROL MODULE(CHECKSUM) ERROR			
P1726	THROTTLE POSITION INPUT - LOSS OF SIGNAL			
P1727	THROTTLE POSITION INPUT - OUT OF RANGE			
P1728	EMC - OPEN/SHORT TO BATTERY			
P1729	EMC - SHORT TO GROUND			
P1730	FRONT SPEED SENSOR - LOW INPUT			
P1731	FRONT SPEED SENSOR - HIGH INPUT			
P1732	REAR SPEED SENSOR - LOW INPUT			
P1733	REAR SPEED SPEED SENSOR - HIGH INPUT			
P1734	SPEED SENSOR REFERENCE - LOW INPUT			
P1735	SPEED SENSOR REFERENCE - HIGH INPUT			
P1736	SHIFT MOTOR - OPEN			
P1737	SHIFT MOTOR - OPEN/SHORT TO GROUND			
P1738	SHIFT SYSTEM TIMEOUT			
P1739	GENERAL POSITION ENCODER FAULT			
P1740	POSITION 1 - SHORT TO GROUND			
وليت P1741 ود)	POSITION 2 - SHORT TO GROUND			
P1742	POSITION 3 - SHORT TO GROUND			
P1743 0 9 0 0	POSITION 4 - SHORT TO GROUND a la guada de la companya de la compa			

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Transfer Case Assembly

DTC Memory Erase

DTC memory in case of the Active Torque Transfer type is erased by the Hi-Scan.

SELF-DIAGNOSIS PROCEDURE FOR EST(MANUAL)

- 1. Connect a Hi-scan to the self-diagnosis connector on the engine room OBD connector. (the lower inside of crash pad in driver's side)
- 2. Turn the ignition ON.
- 3. Select and operate according to the instructions on the Hi-scan screen.
 - 1) Select "KIA VEHICLE DIAGNOSIS".
 - 2) Select "VEHICLE NAME".
 - 3) Select "4WD SYSTEM".



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Select "01.DIAGNOSTIC TROUBLE CODES". It shows diagnostic trouble code list.

MODEL : SORENTO SYSTEM : 4WD	2004M Y		
4WD(EST-MA	NUAL)		
01. DIAGNOSTIC TROUBLE CODES			
01. DIAGNOSTIC TR	OUBLE CODES		
01. DIAGNOSTIC TR	OUBLE CODES		
01. DIAGNOSTIC TR	OUBLE CODES		

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PART

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BKAE091C

1.1 DIAGNOSTIC TROUBLE CODES

<DIAG. TERMINAL IN ENGINE ROOM>

1 2 3 4

5 6 7 8 9 10 11 12

13 14 15 16 17 18 19 20

MIL CODE COUNTER : 000

JUMP PIN '8' TO PIN '4'. PRESS 'ESC'

FLOW

____,

HELP ERAS

001. TCCU MODULE 010. SHIFT MOTOR

011. MAGNETIC S/CLUTCH



1. Select and operate according to the instructions on the Hi-scan screen. (Refer to EST(MANUAL) procedures)



EST standard input and output value in TCCM

N	00:		Condition	2.0 . 0 u	Signal	Domorko
IN	0.	items	Condition	Туре	Level	Remarks
1	A1	MOTOR OUTPUT	IDLE("N")	DC	Vbatt	*Current :
		(2H-4H-4L)		↑	0V	INRUSH(+) : 4.64A
2	A2	MOTOR OUTPUT	IDLE("N")	DC	Vbatt	OPERATION : 0.6
		(2H-4H-4L)		↑	0V	A
3	A3	GND				
4	A4	CLUTCH COIL	IDLE	DC	Vbatt	*Current : 4.28A
			(2H→4H→4L)	↑	0V	
5	A5	POSITION 1 MTR	IDLE (P/R/N/D/2/L)	2H 2H→4H 4H→4L	CODE : 1010 CODE : 0011 CODE : 1100 LOGIC HI(1) : 5V LOGIC LO(0) : 0.5V or less	*MTR POS. CODE : 1/2/3/4 = XXXX (1=5V dc) (o≤0.5V dc)

Transfer System

Transfer Case Assembly

6 A6 SPEED SENSOR IDLE

						HI : 16.4V LOW : -6.4V
7	A7	2H SW.	SW OFF	DC	4.5 ~ 5.5V	
			SW ON	↑ (0.5V or less	
8	A8	4H DISPLAY	SW OFF	DC	Vbatt	
			SW ON	↑	0.5V or less	
9	A9	BATT	IGN OFF	DC	Vbatt	
			IGN ON	↑ (Vbatt	
10	A10	BATT	IGN OFF	DC	Vbatt	
			IGN ON	↑ (Vbatt	
11	A11	GND				
12	A12	POSITION 2 MTR	IDLE (P/R/N/D/2/L)	2H 2H→4H 4H→4L	CODE : 1010 CODE : 0011 CODE : 1100 LOGIC HI(1) : 5V LOGIC LO(0) : 0.5V or less	*MTR POS. CODE : 1/2/3/4 = XXXX (1=5V dc) (o≤0.5V dc)
13	A13	4L SW	SW OFF	DC	4.5 ~ 5.5V	
	حدوا	، (مسئولیت م	SW ON	جيهان<	0.5V or less	
14	A14	INHIBITOR SW(AT)	N	DC	ov	
	بران	CLUTCH INTERLO- CK SW(MT)	P/R/D/2/L	R., O∱CULO	Vbatt	
15	A15	4L DISPLAY	IDL("N")	DC	Vbatt	
				\uparrow	0V	
16	A16	MOTOR OUTPUT	IDL("N")	DC	Vbatt	
		(4L→4H→2H)		↑	0V	
21	A21	POSITION 3 MTR	IDLE (P/R/N/D/2/L)	2H 2H→4H 4H→4L	CODE : 1010 CODE : 0011 CODE : 1100 LOGIC HI(1) : 5V LOGIC LO(0) : 0.5V or less	*MTR POS. CODE : 1/2/3/4 = XXXX (1=5V dc) (o≦0.5V dc)
22	A22	DIA.DISPLAY	In comm.	PULSE	4V or more	
23	A23	FRRD SOLENOID	IDLE	OFF		
			(2H→4H)	ON		

PULSE

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*VSS of 60KPH :

Transfer System

WARNING LAMP OPERATING CONDITIONS

literee e	O an allthis a	INDICATOR		Description
items	Condition	4LOW	W/Lamp	Description
TPS	OPEN OR SHO- RT(GND)	OFF	OFF	 No warning lamp blink or ON AUTO ↔ 4LOW shift is possible
SHIFT MOTOR	OPEN	OFF	Blink	 Warning lamp blinks after 1 sec. since the fault is occurred. Fail at the "AUTO mode" AUTO mode holding "4LOW" lamp blinks if "4L" is selected Fail at the "4LOW mode" 4L mode holding "4LOW lamp" blinks if "AUTO" is selected Fail at the fault is repaired, shift prevention i s still existed. If IG. ON again, system is operated normally.
SHIFT MOTOR POSITI- ON SENSOR (1), (2), (3), (4) (موليت محدود) فودرو در ايران	OPEN Short to battery SHORT(GND)	OFF خودرو میتال	Blink	 Warning lamp blinks after 1 sec. since the fault is occurred. Fail at the "AUTO mode" AUTO mode holding "4LOW" lamp blinks if "4L" is selected Fail at the "4LOW mode" 4L mode holding "4LOW" lamp blinks if "AUTO" is selected Fail at the fault is repaired, shift prevention i s still existed. If IG. ON again, system is operated normally.
FRT SPEED SENSOR RR SPEED SENSOR	OPEN OPEN	OFF	OFF OFF	 Warning lamp blinks after 0.5 sec. since the fault i- s occurred. Fail at the "AUTO mode" AUTO mode holding "4LOW" lamp blinks if "4L" is selected Fail at the "4LOW mode" 4L mode holding "4LOW" lamp blinks if "AUTO" is selected Fail at the fault is repaired, shift prevention i s still existed. If IG. ON again, system is operated normally.

Transfer Case Assembly

EMC	OPEN	OFF	Blink	
(ELECTRO MAGNETIC CLUTCH)	SHORT(GND)	OFF	Blink	 Warning lamp blinks after 0.8 sec. since the fault i- s occurred. Fail at the "AUTO mode" "AUTO" mode holding "4LOW" lamp blinks if "4L" is selected Fail at the "4LOW mode" 4L mode holding "4LOW" lamp blinks if "AUTO" is selected Fail at the fault is repaired, shift prevention i s still existed. If IG. ON again, system is operated normally.

DTC LIST AND FAILSAFE

No.	Description	P-code	Failure effect	Fail-safe	W/Lamp
1	EEPROM check sum fault	P1725	TOD	Default calibration data	-
2	TPS loss of signal	P1726	TOD (TPS Idle)	TOD Determined by wheel slip only	OFF
3	TPS out of range	P1727	TOD (TPS Idle)	TOD Determined by wheel slip only	OFF
4	EMC open/shorted to battery	P1728	TOD Halted (2WD)	None	Blink
5	EMC shorted to ground	P1729	TOD Halted (2WD)	None	Blink
6	Front speed sensor voltage I ow	P1730	رکت دیtop تال خو	4H mode fail, Rear speed sens- or, EMC Touch off level fixing. 4	OFF
7	Front speed sensor voltage high	P1731	ولین سام ^{TOD} دیںجین	L Mode fail, EMC Maximum lev- el fixing.	OFF
8	Rear speed sensor voltage I- ow	P1732	TOD	4H mode fail, Front speed sens- or, EMC Touch off level fixing. 4	OFF
9	Rear speed sensor voltage high	P1733	TOD	L Mode fail, EMC Maximum lev- el fixing.	OFF
10	Vehicle speed sensor refere- nce voltage low	P1734	TOD	4H mode fail, Zero speed senso- r, EMC Touch off level fixing. 4L	OFF
11	Vehicle speed sensor refere- nce voltage high	P1735	TOD	Mode fail, EMC Maximum level fixing.	OFF
12	Shift motor open/shorted to battery	P1736	Electric motor shifting (4H→4L→4H)	No shifts	Blink
13	Shift motor open/shorted to ground	P1737	Electric motor shifting (4H→4L→4H)	No shifts	Blink
14	Shift system timeout	P1738	Electric motor shifting (4H→4L→4H)	No shifts	Blink
15	General position encoder fa- ult	P1739	Electric motor shifting (4H→4L→4H)	No shifts	OFF

Transfer System

16	Position 1 shorted to ground		Electric motor shifting (4H→4L→4H)	No shifts	
17	Position 2 shorted to ground	D1740	Electric motor shifting (4H→4L→4H)	No shifts	
18	Position 3 shorted to ground	P1740	Electric motor shifting (4H→4L→4H)	No shifts	UFF
19	Position 4 shorted to ground		Electric motor shifting (4H→4L→4H)	No shifts	

STANDARD INPUT AND OUTPUT VALUE IN TODCM

N	~	Itomo	Condition	Signal		Domorko
	0.	nems	Condition	Туре	Level	Remarks
1	A1	MOTOR OUTPUT	IDLE("N")	DC	Vbatt	
		(HI-LOW)		↑	0V	
2	A2	MOTOR OUTPUT	IDLE("N")	DC	Vbatt	
		(LOW-HI)		↑	0V	
3	A3	EMC	Vehicle drivi- ng	PULSE (PWM)	Vbatt ov	*4LOW DUTY(-): 88.72%
()	حدو	› (مسئوليت م	درو سامانه	• •• يتال خور	FREQ : 50Hz DUTY(-) : 0~88%	
4	A4	BATT	IGN OFF	DC	Vbatt	
	بران	ناران خودرو در ا	IGN ON	ﻪ دېجية	Vbatt-0-99	
5	A5	IGN 1	IGN OFF	DC	0V	
			IGN ON	↑	Vbatt	
6	B1	ENCODER GND				
7	B2	DIAGNOSTIC DISP-	LAMP OFF	DC	Vbatt	
		LAY	LAMP ON	↑	0.5V or less	
8	В3	TPS (PWM)	ACCEL C.T & W.O.T	PWM	HI : 4V MIN LOW : 0.9V MAX FREQ : 100Hz DUTY(-) : C.T-10%, W.O.T-83%	
9	B4	AUTO/LOW SW.	IDLE (A/T LEVER "N")	AUTO LOW	4V or more 0.9V or less (AUTO mode : 4V or more)	
10	B5	SHIFT MOTOR PO- SITION 2	IDLE (A/T LEVER "N")	→AUTO →LOW	CODE : 0010 \rightarrow 0000 CODE : 0101 \rightarrow 0000 LOGIC HI(1) : 4.5V or more LOGIC LO(0) : 0.5V or less	*MTR POS. CODE : 1/2/3/4 = XXXX

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11	B6	FRT SPEED SNSR	Vehicle drivi- ng	PULSE	4V or more 	*VSS 60KPH : 985Hz
12	B7	N.A				
13	B8	SPEED SNSR GND				
14	A6	MOTOR OUTPUT	IDLE("N")	DC	Vbatt	
		(HI-LOW)		\uparrow	0V	
15	A7	MOTOR OUTPUT	IDLE("N")	DC	Vbatt	
		(LOW-HI)		\uparrow	0V	
16	A8	SPEED REFEREN-	IGN OFF	DC	0.9V or less	
		CE	IGN ON	\uparrow	4.75~5.25V	
17	A9	GND FOR ECU				
18	A10	GND FOR ECU				
19	A11	BATT	IGN OFF	DC	Vbatt	0
		59	IGN ON	\uparrow	Vbatt	
20	A12	K-LINE (مسئولیت م	In comm. (10.4Kbps)	PULSE	LOGIC "0" : Vbatt 20% or less LOGIC "1" : Vbatt 80% or more	
21	B9	4LOW DISPLAY	SW OFF	DC	Vbatt	*IGN ON :
	بران	باران خودرو در ا	SW ON	ﻪ د <u>†</u> جيت	0.5V or less	Turned on for 3sec
22	B10	N.A				
23	B11	N.A				
24	B12	TRANS. NEUTRAL	Ν	DC	0.9V or less	
			P/R/D/2/L	↑	4.5 ~5.5V	
25	B13	ABS INPUT	ABS OFF	DC	4.5 ∼5.5V	
			ABS ON	\uparrow	0.9V or less	
26	B14	BRAKE SW.	SW OFF	DC	0.9V or less	
			SW ON	\uparrow	Vbatt	
27	B15	SHIFT MOTOR PO- SITION 1	IDLE (A/T LEVER "N")	→AUTO →LOW	CODE : 0010 \rightarrow 0000 CODE : 0101 \rightarrow 0000 LOGIC HI(1) : 4.5V or more LOGIC LO(0) : 0.5V or less	*MTR POS. CODE : 1/2/3/4 = XXXX
28	B16	SHIFT MOTOR PO- SITION 3	IDLE (A/T LEVER "N")	→AUTO →LOW	CODE : 0010 \rightarrow 0000 CODE : 0101 \rightarrow 0000 LOGIC HI(1) : 4.5V or more LOGIC LO(0) : 0.5V or less	*MTR POS. CODE : 1/2/3/4 = XXXX

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29	B17	RR SPEED SNSR	Vehicle drivi- ng	PULSE	4V or more 4V or more 0-0.9V 30PULSE/PROPSHAFT REV. DUTY(-) : 50%	*VSS 60KPH : 966Hz
30	B18	SHIFT MOTOR PO- SITION 4	IDLE (A/T LEVER "N")	→AUTO →LOW	CODE : 0010 \rightarrow 0000 CODE : 0101 \rightarrow 0000 LOGIC HI(1) : 4.5V or more LOGIC LO(0) : 0.5V or less	*MTR POS. CODE : 1/2/3/4 = XXXX

INSPECTION PROCEDURES FOR DIAGNOSTIC TROUBLE CODES

DESCRIPTIONS

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TOD control unit starts self-diagnostic function after the ignition is switched ON.

If TOD control unit detects failure for each circuit and component by comparing condition of the system with limited condition set inside TOD control unit, TOD control unit stores the failure code.

The failure code stored in TOD control unit can be confirmed by scan tool and then outputs the four-digit code to the scan tool when the scan tool is connected to TOD data link connector in the engine room.

Please refer to the self-diagnosis procedure for TOD(auto) in detail as followed.

DIAGNOSTIC TROUBLE CODE SUMMARY

CODE	POSSIBLE CAUSE	REMEDY
P1725	EEPROM CHECKSUM error - When EEPROM CHECKSUM of TCCU is error	 Measure TCCU supply voltage Inspect ground Inspect connection of relevant connector Inspect malfunction of TCCU
P1726	No signal of throttle position When the signal of throttle position is not recognized 	 Inspect communication line connection between engine ECU and TCCU Diagnose defect of engine ECU Inspect malfunction of TCCU
P1727	Abnormality of throttle position signal - When the throttle position signal is error	 Inspect communication line connection between engine ECU and TCCU Diagnose defect of engine ECU

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P1728	Open/short circuit of electro magnetic clutch(EMC) - When the electro magnetic clutch(EMC), the relevant connector or the wire is error	1. 2. 3. 4.	 Measure supply voltage of EMC Inspection condition: IG ON / Engine driving Specified value Terminal voltage between TCCU No.4 and No.17 : 11-15 V Measure resistance of EMC(Item condition) Inspection condition: With disconnecting the connector, inspect the wire side connector pin Specified value Terminal resistance between TCCU pin No.3 and No.17 : 2.5 Ω Terminal voltage between TCCU pin No. 3 and No.17: LOW : 0V, HIGH : 11-15V Inspect open/short circuit of cable related to the electro magnetic clutch(EMC) Inspect abnormal connection of connector related to EMC
P1729	Open(GND) circuit of EMC - When the EMC or the relevant connector or the wire is error	1. 2.	 Inspect supply voltage of EMC Inspection condition: IG ON / Engine driving Specified value Terminal voltage between TCCU No.4 and No.17 : 11-15 V Measure resistance of EMC(Item condition) Specified value Terminal resistance between TCCU pin No.3 and No.17 : 2.5 Ω Terminal voltage between TCCU pin No. 3 and No.17 : LOW : 0V, HIGH : 11-15V
P1730	 Low voltage of front speed sensor When front speed sensor is too low output voltage 	1. 2. 3.	 Inspect output waveform of front speed sensor Inspection condition: At driving Specified value Terminal voltage between TCCU pin No. 11 and No.13: LOW : below 0.9V, HIGH : 4.75-5.25V Inspect abnormal connection of the relevant connector Inspect open/short circuit related to cable
P1731	 High voltage of front speed sensor When front speed sensor is too high output voltage 	1. 2. 3.	 Inspect output waveform of front speed sensor Inspection condition: At driving Specified value Terminal voltage between TCCU pin No. 11 and No.13: LOW : below 0.9V, HIGH : 4.75-5.25V Inspect abnormal connection of the relevant connector Inspect open/short circuit related to cable

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P1732	Low voltage of rear speed sensor - When rear speed sensor is too low outp- ut voltage	 Inspect output waveform of rear speed sensor Inspection condition: At driving Specified value Terminal voltage between TCCU pin No. 29 and 13 : LO-W : below 0.9V, HIGH : 4.75-5.25V Inspect abnormal connection of the relevant connector Inspect open/short circuit related to cable
P1733	High voltage of rear speed sensor - When rear speed sensor is too high out- put voltage	 Inspect output waveform of rear speed sensor Inspection condition: At driving Specified value Terminal voltage between TCCU pin No. 29 and 13 : LO-W : below 0.9V, HIGH : 4.75-5.25V Inspect abnormal connection of the relevant connector Inspect open/short circuit related to cable
P1734	Low standard voltage of speed sensor - When speed sensor is too low supply vo- Itage	 Measure supply voltage of speed sensor Inspection condition: IG ON / At driving Specified value Terminal voltage between TCCU pin No. 16 and 13 : 4.7 5-5.25V Inspect abnormal connection of the relevant connector Inspect open/short circuit related to cable
(59 P1735	High standard voltage of speed sensor - When speed sensor is too high supply v- oltage	 Measure supply voltage of speed sensor Inspection condition: IG ON / At driving Specified value Terminal voltage between TCCU pin No. 16 and 13 : 4.7 5-5.25V Inspect abnormal connection of the relevant connector Inspect open/short circuit related to cable
P1736	Open/short(power) circuit of shift motor - When the shift motor or the wire of motor is error	 Inspect resistance of shift motor Inspection condition: With disconnecting the connector, inspect the wire side connector pin Specified value

Transfer Case Assembly

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P1737	Shift motor output short (GND) - When the shift motor or the wire of motor is error	 Inspect resistance of shift motor Inspection condition: With disconnecting the connector, inspect the wire side connector pin Specified value
P1738	Shift system time out - When shift system is error	 Remove the motor and then connect the connector which of condition operate motor. If motor is operated, inspect transfer case assembly but if not, replace motor. Inspect open/short circuit related to cable Inspect defective connection of the relevant connector
P1739	Malfunction of position encoder - When the position encoder that recogniz- es shift motor is error	 Inspect open/short circuit related to cable Inspect abnormal connection of the relevant connector Inspect encoder
P1 <mark>740</mark>	 Short circuit of "1" position (GND) At short circuit between encoder signal No.1 and GND 	 Inspect open/short circuit related to cable Inspect abnormal connection of the relevant connector Inspect encoder
P1741	 Short circuit of "2" position (GND) At short circuit between encoder signal No.2 and GND 	 Inspect open/short circuit related to cable Inspect abnormal connection of the relevant connector Inspect encoder
P1742	 Short circuit of "3" position (GND) At short circuit between encoder signal No.3 and GND 	 Inspect open/short circuit related to cable Inspect abnormal connection of the relevant connector Inspect encoder
P1743	 Short circuit of "4" position (GND) At short circuit between encoder signal No.4 and GND 	 Inspect open/short circuit related to cable Inspect abnormal connection of the relevant connector Inspect encoder

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SERVICE ADJUSTMENT PROCEDURES FLUID LEVEL INSPECTION

- 1. Wipe fluid level plug and surrounding area clean.
- 2. Remove fluid level plug.
- 3. When transfer case is full, lubricant will just drip out fluid level plug opening.
- 4. Add approved lubricant if required.
- Install fluid level plug and torque to 20 30 N·m (14 22 lb·ft).

• To check or drain the lubricant, the transfer case should be warm.

This is best done shortly after shutdown.

• Do not use an impact wrench to remove or install the fill or drain plugs since this will damage female threads in transfer case cover.

LMAC330A

Transfer System

FLUID REPLACEMENT

- 1. Wipe fluid level and drain plug and surrounding areas clean.
- 2. Place suitable container under transfer case.
- 3. Remove drain plug.
- 4. Remove fluid level plug.
- 5. Allow all lubricant to drain.
- 6. Install drain plug and torque to 20 30 N·m (14 22 lb·ft).
- 7. Add approved lubricant through fluid level plug opening until lubricant just begins to drip back out of opening.
- Install fluid level plug and torque to 20 30 N·m (14 22 lb·ft).

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LMAC330B

Transfer Case Assembly

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P1725

F								
INSPECTION DIAGNOSTION TOD CONTRO	N PRC C TROUBLE	CEDURES F CODE CHECKSUM)	OR					
P17	725	TOD CONTROL MOD	ULE(CH	ECKSUM)	ERROR			
		COMMENT				PROE	BABLE CAUSE	
When IG switcl oes not turn O scan tool.	h is turned to C FF. Also diagn	0N, "4WD CHECK" war ostic trouble code No.F	ning lam P1725 is	p turns ON output wh	N and then d- nen using the	 Malfunction CKSUM Malfunction 	on of EEPRON	N CHE-
Confirm and de Connect the sca	lete DTC code n tool to vehicle ar	d delete DTC after confirmin	g					
Symptom simu Turn IG ON an No DTC	ulation test	n test after confirming		C Tempo	orary connection	n failure of connect	or]
Inspect supply	voltage		-					
Turn IG ON after Measure the su of TOD ECU co Specified va Remove the ma	er disconnect TOD upply voltage betw onnector using mul alue: 11~14V(DC) CK alfunction of betwe	ECU connector, een NO. 5 and NO. 17/18 ti-tester block of the start of	میتال نه ديع	Inspect the Inspect if the	fuse e No. 20 fuse(10 OK	DA) in the internal f	fuse box is brown NG the fuse(10A)	
		•	-					
Symptom simu	lation test	·						
Perform sympt	om test after confi	ming no DTC		Tempor	ary connection f	failure of connecto	r	
	DT	n	J					
Inspect open c	ircuit of TOD ECU	3	ок		FOD ECU and c	onnector		٦
Turn IG ON and Then, check the chassis using n	d disconnect TOD e open circuit betw nultitester	ECU connector. een pin NO. 17/18 and		Inspect o Inspect c	pen/short circui onnectors relate	t of TOD ECU ed to TOD ECU	T	
Specified vi	alue: Below 0.3Ω		Г	Temporary		l	NG	
	NG		- L	failure of co	onnector		↓	
Inspect malfun	ction of TOD ECU			Replace r	IEW TOD ECU to	emporary and per	form symptom	
Inspect the iten - When turning turn off and ke - When operation	ns as followed IG ON, "4WD CH eep turning ON ng 4H/4L switch, n	ECK" warning lamp don't o shift function of motor		using scaTempora	n tool. If DTC is	n't appeared, repla	ICH TOD ECU	

BKAE100A

WD-24

021 62 99 92 92

Transfer System

P1726

THROTTLE POSITION I	NPUT	
P1726	THROTTLE POSITION INPUT-LOSS OF SIGNAL	
P1727	THROTTLE POSITION INPUT-OUT OF RANGE	
	COMMENT	PROBABLE CAUSE
The diagnostic trouble code N	lo.P1726 is output when using scan tool.	 Malfunction of TOD ECU Malfunction of CAN communication line Malfunction of engline ECU



BKAE100B

Transfer Case Assembly

WD-25

P1728

EMC				
P1728	EMC-OPEN/SHORT	ΓΟ ΒΑΤΤΕ	RY	
P1729	EMC-SHORT TO GRO	OUND		
	COMMENT			PROBABLE CAUSE
When IG switch is turned to oes not turn OFF. Also the n using the scan tool.	ON, "4WD CHECK" war diagnostic trouble code N	ning lamp lo.P1728,	turns ON and then d- P1729 is output whe-	 Malfunction of electronic magnet clutch Malfunction of connector or wiree
Confirm and delete DTC code		7		
Connect the scan tool to vehicle	and delete DTC after confirmir	ng		
·				
Symptom simulation test			Temperation	failure of compositor
Turn IG ON and perform symp No DTC	tom test after confirming			
t		NG	Densis the molfunction	of botween TOD FOLL and
Inspect relevant connectors			EMC connector	or between TOD ECO and
Inspect the connecting of TOD clutch coil(7) connector	ECU, speed sensor and			
سئوليت محدود)	خودر و سامانه (می	NG	Symptom simulation test	
	ок 🚽 🔊 🗸	0	Turn IG ON and perform	symptom test after confirming
Inspect supply voltage	م تا التو م حکولات	I. S. A. H.		
Turn IG ON after connecting To Measure the supply voltage be NO. 17/18 of TOD ECU connect	OD ECU connector. etween pin NO. 4/19 and ctor using multitester	NG	 Inspect battery voltage Check for open circuit or wire related to ECM 	f relevant fuse(20A) and inspect
Specified value: 11~15V(D	C)			
	к	_		
Inspect resistance				
Turn IG OFF and disconnect T	OD ECU connector.		Inspect wire related to E	ECM
Measure the resistance betwee side using multi-tester	en NO. 3 and NO. 17 of wire		 If is 0 Ω(ZERO), short if If is Ω, open circuit Benair or replace the x 	
● Specified value: 2.5Ω				
	ж	_		
Inspect ECM operating voltage	9			
Turn IG ON and measure the v TOD ECU connector NO. 3 and	voltage between d NO.17 with oscilloscope		Replace new TOD ECU tel using scan tool. If DTC isn'	mporary and perform symptom 't appeared, replace TOD ECU
Specified value : LOW: 0V HIGH:11-	(DC) •15V(DC)	NG	Repair the wire or replace	e the EMC

BKAE100C

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WD-26

Transfer System

е

P1730

SPEED SENSOR				
P1730	FRONT SPEED SENSOR-LOW INPUT			
P1731	FRONT SPEED SENSOR-HIGH INPUT			
P1732	REAR SPEED SENSOR-LOW INPUT			
P1733	REAR SPEED SENSOR-HIGH INPUT			
P1734	SPEED SENSOR REFERENCE-LOW INPUT			
P1735	SPEED SENSOR REFERENCE-HIGH INPUT			
	COMMENT	PROBABLE CAUSE		
When IG switch is turned oes not turn OFF. Also the using the scan tool.	to ON, "4WD CHECK" warning lamp turns ON and then d- e diagnostic trouble code No.P1730~P1735 is output wh-	 Malfunction of speed sensor(F- ront/Rear) Malfunction of power supply Malfunction of connector or wir- 		

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اولین سامانه دیجیتال تعمیرکاران خودرو در ایران

Confirm and delete DTC code

Symptom simulation test

Inspect supply voltage

Inspect output waveform

Output waveform: OK

Inspect output voltage

 Specified value: LOW: below 0.9V(DC) HIGH: 4.75~5.25V(DC)

using multi-tester

No DTC

Transfer Case Assembly

Connect the scan tool to vehicle and delete DTC after confirming

DTC

Turn IG ON and perform symptom test after confirming

Turn IG ON and then measure the supply voltage

Specified value: 4.75~5.25V(DC)

sensor(Front/Rear) using scan tool

sensor(Front/Rear) using multi-tester

Front: NO.11 and No.13 of TOD connector

Rear: NO.29 and No.13 of TOD connector

between pin NO.16 and NO.13 of TOD ECU connector

While driving vehicle, inspect the waveform of speed

OK

OK

OK

Replace new TOD ECU temporary and perform symptom using scan tool. If DTC isn't appeared, replace TOD ECU

Turn IG ON and then measure output voltage of speed

NO DTC

NG

NG

NG

NG

EMC connector

No DTC

Voltage

(Front/Rear)

0

Inspect wire related to sensor

OK

Temporary connection

failure of connector

Symptom simulation test

Replace the relevant speed sensor

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Temporary connection failure of connector	nector

Angle

NG

Replace the relevant

speed sensor

Repair the malfunction of between TOD ECU and

Turn IG ON and perform symptom test after confirming

Repair the open/short circuit related to speed sensor

BKAE100D

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WD-27

WD-28

Transfer System

P1736

SHIFT MOTOR				
P1736	SHIFT MOTOR-OPEN			
P1737	SHIFT MOTOR-OPEN	/SHORT	TO GROUND	
P1738	SHIFT SYSTEM TIME	OUT		
	COMMENT			PROBABLE CAUSE
When "4H/4L switch" is sh time then turns on. And "4 trouble code No.P1736~P "4H/4L switch", "4H/4L swi	ifted from 4H to 4L, "4L" la WD CHECK" warning lam 1738 is output when using tch" isn't shifted.	amp does p turns or the scan	not turn on for some n. Also the diagnostic tool. When operating	 Malfunction of shift motor Malfunction of power supply Malfunction of connector Open/short circuit of wire
Confirm and delete DTC code				
Connect the scan tool to vehicle	e and delete DTC after confirming	3		
Symptom simulation test				
Turn IG ON and perform sym	ptom test after confirming		Temporary connection	failure of connector
No DTC	<u> </u>			
	DTC	NG	Bepair the malfunction	of between TOD ECU and shift
Inspect supply voltage		•	motor connector	
The AT lever is shifted to "N" a Measure motor HI-LO voltage (or NO.2/15) and pin NO.17/1	and then Turn IG ON. between pin NO.1/16 18 of TOD ECU connector	جيتال	شرکت دی	
Specified value: 11~14V(E)))))))))))))))))))))))))))))))))))))))		Symptom simulation test	t
L CONTRACTOR	ок 了	NG	Turn IG ON and perform No DTC	n symptom test after confirming
Inspect open/short circuit	•]		
Turn IG OFF and disconnect Then, check the short circuit b and 2/15 of wire connector. Then, check the short circuit b GND, 2/15 and chassis(GND)	FOD ECU connector. Detween pin NO.1 and 2/15, 14 Detween pin no. 1/14 and	NG	Repair the wire between	en TOD ECU and shift motor
Specified value: 0 Ω			Symptom simulation te	st
	ок	- NG	Perform symptom test	after confirming no DTC
Inspect resistance	¥			
Turn IG OFF and disconnect T measure the resistance betwee TOD ECU connector and disc transfer case side and measu NO.G and NO. B of motor con ● Specified value: 1~250 Q	TOD ECU connector and en NO.1/14 and NO.2/15 of onnect motor connector of re resistance between pin nector	NG	Repair or replace the st	hift motor
	OK	•		
Inspect and repair transfer ca	se assembly	<u>ок</u>	Replace new TOD ECU te using scan tool. If DTC isn	emporary and perform symptom o't appeared, replace TOD ECU

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Transfer Case Assembly

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WD-29

BKAE100E

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Transfer System

P1739

POSITION ENCODER						
P1739	GENERAL POSITION	ENCODE	RFAULT			
P1740	POSITION 1 - SHORT TO GROUND					
P1741	POSITION 2 - SHORT TO GROUND					
P1742	POSITION 3 - SHORT	TO GRO	UND			
P1743	POSITION 4 - SHORT	TO GRO	UND			
	COMMENT			PROBABLE CAUSE		
When IG switch is turned to C oes not turn OFF. Also the di en using the scan tool.	DN, "4WD CHECK" warr agnostic trouble code N	ning lamp lo.P1739 ⁻	turns ON and then d- ~P1743 is output wh-	 Malfunction of position encoder Short circuit between each wire and ground 		
Confirm and delete DTC code Connect the scan tool to vehicle ar	nd delete DTC after confirming					
·		-				
Symptom simulation test	• •	NO DTC		5-11		
Turn IG ON and perform sympton No DTC	m test after confirming		Iemporary connection			
DT	c ••	NG				
Inspect short circuit of encoder	خودرو سامانه (ه	جيتال	Repair or replace	to ground		
Turn IG OFF and disconnect TOE Check the short circuit between N NO.10(position2), NO.28(position of TOD ECU connector wire side multitester	DECU connector. NO.27(position1), 3), NO.6(position return) and chassis(GND) using	انه دي	اولين ساه			
● Specified value: Over 0 Ω		NG	Symptom simulation tes	t		
ок	•		Turn IG ON and perform	symptom test after confirming		
Inspect open circuit of encoder						
Turn IG ON and connect TOD EC AT level to "N" position	U connector and shift	NG	 Repair the open/short ci (Front/Rear) 	ircuit related to speed sensor		
- When "4H/4L"switch is in "4H", o NO.6 and 10, NO.6 and 30 of TC - When 4H/4L switch is in "4L", ch NO.6 and 27, NO. 6 and 28 of T	check for continuity between DD ECU connector neck for continuity between OD ECU connector					
• ок						
Replace motor assembly becaus encoder	e of malfunction of position	ок	Replace new TOD ECU te using scan tool. If DTC isn	emporary and perform symptom 't appeared, replace TOD ECU		

BKAE100F

MOTICE

With the connector connected when the IG is ON, do not operate the switches while measuring resistance or the continuity test corresponding to the connector. If the switches are operated, be careful that the tester may be damaged or injured due to excessive current in the connector momentarily.

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Transfer Case Assembly

WD-31

Abnormality of shifting operation

		_
NO	DT	С

Abnormality of shifting operation

COMMENT	PROBABLE CAUSE
When "4H/4L"switch is shifted from 4H to 4L, "4L" indicating lamp is blinking contin- uously.	Failure of system



BKAE100G

Transfer System

Transfer Case

4WD SYSTEM DESCRIPTION

Drive type	Drive item	Drive mod - e	Drive status	Useful condition
Electric Shift Transf- er	Drive mode	2H	2WD, Rear wheel driv- e	Use on the roadway
(EST type)		4H	4WD HIGH	 Use on the off-road or snowy and rainy roa- d having slippery road surface. When turning on the roadway at low speed, vibration and noise happens by tight corner braking.
		4L	4WD LOW	Use in the condition which driving force is req- uired like escaping from rough way and towing.
	Transfer	2H ↔ 4H	2WD ↔ 4WD	Possible to transfer 2WD into 4WD and vice v- ersa at 80kph or below during driving.
Q]D	خم	4H ↔ 4WD (L)	4WD(H) ↔ 4WD(L)	 Necessary to stop the vehicle for transfer M/T vehicle : Transfer the switch after pressing the c-lutch pedal. A/T vehicle : Transfer the switch after positioning the A/T lever to "N".
یت محدود)	ہ (مسئوا	درو سامان	ئت دیجیتال خو	• All vehicles with 4L mode should stop the vehicle for transfer.
Active Torque Tran- sfer (ATT type)	Drive mode	AUTO	2WD ↔ 4WD	 Use on the various road surfaces including roadway, off-road, or snowy and rainy road haring slippery road surface. Using multiple clutch, control the revolution difference between front and rear wheels electronically. So this mode can correspond to the various road surfaces by controlling the ATT unit automatically.
		LOW	4WD LOW	Refer to 4L of part time.
	Transfer	AUTO ↔ L- OW	4WD(H) ↔ 4WD(L)	 Necessary to stop the vehicle for transfer M/T vehicle : Transfer the switch after pressing the c-lutch pedal. A/T vehicle : Transfer the switch after positioning the A/T lever to "N" All vehicles with 4L mode should stop the vehicle for transfer.

Transfer Case Assembly

EST POWER FLOW

1. 2H Mode (Rear Wheel Drive)



Transfer System

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LMAC250A

2. 4H Mode (Transfer Operation)

WD-34



LMAC250C

Tuenefer Orate

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Transfer Case Assembly

WD-35



LMAC250D

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WD-36

Transfer System



LMAC250E

Transfer Case Assembly

WD-37



LMAC250F

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Transfer System

WD-38

ATT(ACTIVE TORQUE TRANSFER) POWER FLOW

1. AUTO Mode



2. LOW Mode

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Transfer Case Assembly





LMAC260B

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WD-39

LMAC260A

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WD-40

Transfer System



LMAC260C

Transfer Case Assembly

WD-41



LMAC260D

021 62 99 92 92

WD-42



Transfer System



BKAE110A

Transfer Case Assembly

WD-43

1. Input shaft		
2. Input seal	14. Oil seal	
3. Snap ring	15 Speedo gear	
4. Bearing	16. Upper tone wheel	
5. Bearing	17 Bearing	
6. Circular hub	48 Retaining ring	
7. Sun gear	19. Shift fork	
8. Trust plate	50. Return spring	
9. Bushing	51. Hex head bolt	
10. Input shaft sub assembly	52. J clip	
11. Snap ring	53. Hose clamp	
12. Planet pinion shaft	54. Electric motor assembly	
13. Planet carrier	55. Oil seal	
14. Pinion thrust washer	56. Sealing compound	
15. Needle roller bearing	57. Connector pin	
16. Pinion needle spacer	58. Clip locking	
17. Pinion gear	59. Bearing	
18. Carrier	60. Hex head cap screw	
19. Carrier assembly	61. Spacer	
20. Ring gear	32. Lower sprocket	
21. Retaining ring	33. Finish cover	
22. Main shaft	64. Sealing compound	
23. Gerotor pump assembly 👝	65. Case/cover dowel	
24. Main shaft assembly	66. Case sub assembly	
25. Metric bolt	67. Snap ring	
26. Chain	68. Ball bearing	
27. Lower sprocket	69. Oil seal	
28. Lock up collar	70. Output shaft	
29. Sleeve return spring	71. Dust deflector	
30. Torsion spring	72. Front output shaft sub assembly	
31. Lockup hub	73. Electric shift cam	
32. Armature	74. Torsion spring	
33. Retaining ring	75. Shift shaft	
34. Lock up collar assembly	76. Spacer	
35. Coil housing	77. Cam roller	
36. Shift hub	78. Pin shift fork	
37. Cam/coil housing assembly	79. Shift rail	
38. Metric nut	30. Shift fork	
39. Electric coil assemble	31. Reduction hub	
40. Companion flange	32. Shift fork facing	
41. Metric nut	33. Snap ring	
42. washer	34. Shift fork assembly	

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WD-44

COMPONENTS (2)

Transfer System



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Transfer Case Assembly

WD-45

 Snap ring Snap ring Snap ring Bearing Hub Input shaft Thrust plate Sun gear Carrier Reduction hub Main shaft Rotor pump Hose Filter Thrust washer Filter Thrust washer Upper sprocket Lock-up collar Sleeve return spring Clutch housing Clutch housing Slit charfer case Retaining ring Shift fork pad Shift fork pad Shift rail Return spring Lock-up fork Return spring Breather Magnet 	 35. Spacer 36. Torsion spring 37. Shift cam 38. Output shaft 39. Dust defector 40. Oil seal 41. Snap ring 42. Lower sprocket 43. Spacer 44. Chain 45. Retaining ring 46. Bearing 47. Cover 48. Nut 49. Tone wheel 50. Speedo gear 51. Oil seal 52. Companion flange 53. Oil seal 54. Washer 55. Nut 56. Pipe plug 57. Nut 58. 'J' clip 59. Bolt 60. Clip 61. Connector lock 62. Connector 63. Bearing 64. Plug 65. Oil seal 66. Electric motor 67. Bolt 68. Speed sensor 60. Clip 	
32. Breather 33. Magnet	67. Bolt 68. Speed sensor	
34. Shift shaft	69. Bolt	

LMAC270B

Transfer System

ATT (ACTIVE TORQUE TRANSFER) COMPONENTS (1)



BKAE120A

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Transfer Case Assembly

1. 1	Input shaft	43.	Oil seal	
2.	Input seal	44.	Speedo gear	
3. \$	Snap ring	45.	Upper tone wheel	
4 . I	Bearing	46.	Bearing	
5. I	Bearing	47.	Thrust bearing assembly	
6. (Circular hub	48.	Retaining ring	
7. \$	Sun gear	49.	Apply cam	
8. 7	Trust plate	50.	Insulator washer	
9. I	Bushing	51.	Armature	
10.	Input shaft sub assembly	52.	Clutch pack assembly	
11.	Snap ring	53.	Hex head bolt	
12.	Planet pinion shaft	54.	J clip	
13.	Planet carrier	55.	Hose clamp	
14.	Pinion thrust washer	56.	Electric motor assembly	
15.	Needle roller bearing	57.	Oil seal	
16 .	Pinion needle spacer	58.	Sealing compound	
17.	Pinion gear	59.	Bearing	
1 8 .	Carrier	60.	Hex head cap screw	
19.	Carrier assembly	61.	Lower tone wheel	
20.	Ring gear	62.	Lower sprocket	
21.	Retaining ring	63.	Finish cover	
22.	Main shaft	64.	Sealing compound	
23.	Gerotor pump assembly	65.	Case/cover dowel	
24.	Main shaft assembly	66.	Case sub assembly	
25.	Metric bolt	67.	Snap ring	
26.	Chain	68.	Ball bearing	
27.	Lower sprocket	69.	Oil seal	
28.	Upper sprocket	70.	Output shaft	
29.	Bushing	71.	Dust deflector	
30.	Drive sprocket assembly	72.	Front output shaft sub assembly	
31.	Retaining ring	73.	Electric shift cam	
32.	Wave spring	74.	Torsion spring	
33.	Ball	75.	Shift shaft	
34.	Coil housing	76.	Spacer	
35.	Base cam	77.	Cam roller	
36.	Cam/coil housing assembly	78.	Pin shift fork	
37.	Coil electric assembly	79.	Shift rail	
38.	Metric nut	80.	Shift fork	
39.	Companion flange	81.	Reduction hub	
40.	Metric nut	82.	Shift fork facing	
41.	Washer	83.	Snap ring	
42.	Oil seal	84.	Shift fork assembly	

BKAE120B

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WD-47

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WD-48

COMPONENTS (2)

Transfer System



LMAC300A

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Transfer Case Assembly

WD-49

1 Spap ring	29 Magnet
1. Shap ing	30. Shap ring
2. Shap ing	40 Lower cocket
3. Shap ing	40. Lower socket
4. Bearing	41. Lower tone wheel
5. Circula nub	42. Chain
	43. Bearing thrust
7. I hrust plate	44. Retaining ring
8. Sun gear	45. Bearing
9. Carrier	46. Bearing
10. Reduction hub	47. Cover
11. Main shaft	48. Metric bolt
12. Pump	49. Oil seal
13. Thrust washer	50. Washer
14. Hose clamp	51. Metric nut
15. Hose	52. Companion flange
16. Filter	53. Oil seal
17. Electric coil	54. Speedo gear
18. Cam coil housing	55. Upper tone wheel
19. Ball	56. Metric nut
20. Cam apply	57. J-clip
21. Wave spring	58. Hex head bolt
22. Amateur	59. Clip
23. Insulator washer	60. Connector
24. Retaining ring	61. Connector lock
25. Clutch pack	62. Hex head bolt
26. Drive sprocket	63. Upper speed sensor
27. Shift rail	64. Hex head cap screw
28. Shift fork	65. Electric motor
29. Electric shift cam in Cuesci liusus dileturiu	66. Oil seal
30. Electric shift cam	67. Pipe plug
31. Torsion spring	68. Lower speed sensor
32. Shift shaft	
33. Retaining ring	
34. Transfer case	
35. Breather	
36 Output shaft	
37. Dust deflector	

LMAC300B

Transfer System

WD-50

ELECTRIC SHIFT TRANSFER



LMAC242A

Transfer Case Assembly

ACTIVE TORQUE TRANSFER



LMAC244A

WD-51

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WD-52

Transfer System



- 1. Disconnect the battery (-) terminal.
- 2. Remove the front/rear propeller shaft(A,B).



SBLAT8001D

SBLAT8002D

Disconnect the speed sensor connector (A) and 4WD connector (B).





4. Remove the transfer assembly by removing the mounting bolts (8ea) from the transmission side.

Location of the bolts refers to the illustration of contacting surface of the transmission assembly.

Transfer Case Assembly

DISASSEMBLY COMPANION FLANGE

Position transfer case on work bench with rear or cover side up.

Use wooden blocks under front to keep assembly level.

- 1. Remove nut and washer.
- 2. Pull companion flange.
- 3. Remove oil seal.
- 4. If installed, remove two plugs from cover.



LMAC280A

WD-53

021 62 99 92 92

Transfer System

WD-54

EXTERNAL ELECTRIC SHIFT

- 1. Remove bolt (1).
- 2. Remove three bolts (3).
- 3. Remove sensor and harness bracket.
- 4. Remove speed sensor assembly.
- 5. Remove motor assembly.



- Harness bracket & sense
 Sensor assembly
- Sensor assert
 Speed sensor
- 7. O-ring
- 8. Motor assembly
- 9. Cover

COVER ASSEMBLY

1. Remove nine bolts (1). This will free wiring harness clip and identification tag. Use care not to lose identification tag.

LMAC280B

It contains information required for ordering replacement parts.

- 2. Pry at the bosses provided on the cover and transfer case to break the sealant bond loose. Then, lift cover assembly straight up to remove.
- 3. On electric shift units, remove oil seal (5), bearing, three nuts and clutch coil assembly.
- 4. Remove snap ring and pull ball bearing from cover. This will free speedo gear.
- 5. Pull needle bearing from cover.
- 6. Pull oil seal (15) from cover.
- 7. Remove magnet from slot in case.
- 8. Remove return spring from rail shaft.
- 9. Scrap and clean sealant from mating faces of cover and transfer case. Use care not to damage metal faces or allow scrapings to fall into transfercase.



LMAC280C

LOCK SHIFT

- 1. From electric shift only, remove retaining ring and slide clutch housing from shift collar hub.
- 2. Remove shift collar hub from output shaft.
- 3. Together, slide 2W-4W lockup assembly and lockup fork from output shaft and rail shaft. Separate assemblies and remove rail shaft.
- 4. To disassemble 2W-4W lockup assembly, remove snap ring, lockup hub and return spring from lockup collar.
- 5. One-piece, plastic lockup fork replaces earlier fork assembly with metal fork and separate roller parts.



- 1. Shift collar hub
- 2W-4W Lockup assy
 Snap ring
- 4. Lockup hub
- 5. Return spring
- Lockup collar
- Rail shaft
 Lockup fork
 Output shaft
- 10.Retaining ring 11.Clutch housing

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Transfer Case Assembly

WD-55

LMAC280D

CHAIN DRIVE

- 1. Remove snap ring and spacer from output shaft (front).
- Together, slide drive sprocket, driver sprocket and drive chain from output shafts (rear and front). Separate sprockets and chain when outof assembly.



- 1. Snap ring
- Spacer
 Drive sprocket
- 4. Driven sprocket
- 5. Drive chain
- 6. Output shaft (rear)
- Lockup collar

OIL PUMP

- 1. Remove four bolts (2) and retainer. Slide rear pump cover off output shaft.
- 2. Loosen hose clamp and separate hose coupling from pump housing.

Slide pump housing off output shaft.

- 3. Remove hose clamp, hose coupling and strainer.
- 4. Remove two pump pins and spring from output shaft.
- 5. Slide front pump cover off output shaft and remove output shaft.



- Shaft & pump assy
 Bolt
- 3. Pump retainer
- 4. Rear pump cover
- 5. Hose clamp
- Hose coupling
 Pump housing
- 8. Pump pin
- 9. Spring
- 10.Front pump cover
- 11.Output shaft
- 12.Strainer

LMAC280F

REDUCTION SHIFT

- 1. Remove reduction hub and reduction shift fork assembly from transfer case.
- 2. Remove two facings from shift fork assembly.
- 3. Disassemble fork assembly only if parts replacement is required.

Cut plastic retainer to remove, freeing pin and cam roller.



- 1. Reduction hub
- 2. Shift fork facing
- 3. Reduction shift fork assy
- 4. Pin, roller and retainer assy
- 5. Retainer
- 6. Pin
- 7. Cam roller
 - 8. Reduction shift fork

LMAC280G

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Transfer System

WD-56

FRONT OUTPUT SHAFT

- 1. Hold yoke and remove nut and washer. Pull yoke assembly and oil seal.
- 2. Press deflector from yoke only if replacement is required.
- 3. Remove output shaft.



- 1. Nut
- 2. Washer
- З. Oil seal 4.
- Yoke assy 5. Deflector
- 6. Yoke
- Output shaft(front) 7.
- 8. Transfer case

ADAPTER, INPUT SHAFT AND GEAR CARRIER

- 1. Remove breather.
- 2. Remove six bolts (2).

Carefully pry front adapter up to break sealant band with transfer case. Use care not to damage adapter or case.

- 3. Remove adapter assembly, input shaft assembly and gear carrier assembly as an assembled group.
- 4. Holding end of input shaft on workbench press down on adapter while expanding long ends of snap ring.
- 5. Remove snap ring and pump oil seal from front adapter.

Remove pin only if replacement is required.

- 6. Remove retaining ring (8). Pull bearing and thrust washer from end of input shaft assembly. Remove input shaft assembly from gear carrier assembly.
- 7. To disassemble input shaft assembly, pull sleeve bearing and needle bearing from input shaft.
- 8. Remove retaining ring (16), thrust plate end sun gear from planet carrier assembly.



20.Transfer case

LMAC280I

SHIFT CAM (Electric parts)

10.Input shaft assy

1.

4.

5.

6.

7.

- 1. Remove electric shift cam group (1 through 4) from transfer case as an assembly.
- 2. Slide electric shift cam off shift shaft.
- 3. Clamp retainer end of shift shaft.
 - Keeping fingers away from spring ends, pry torsion spring out of engagement with shaft drive tang using a screwdriver.
- 4. Remove torsion spring and spacer from shift shaft.



- 1. Electric shift cam
- Torsion spring 2.
- З. Spacer 4. Shift shaft
- 5. Transfer case

LMAC280J

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Transfer Case Assembly

CASE ASSEMBLY

- 1. Pull oil seal.
- 2. Remove retaining ring and pull ball bearing.
- 3. Remove dowel pins from transfer case only if they are loose or damaged.
- 4. Press ring gear out of transfer case only if ring gear must be replaced.



- 1. Transfer case assembly
- 2. Oil seal
- 3. Retaining ring
- 4. Ball bearing
- 5. Dowel pin
- Ring gear
 Transfer case

se

LMAC280K

DISASSEMBLY

- 1. Remove the transfer case from the vehicle.
- 2. Remove the flange washer and nut.
- 3. Disconnect the shift motor/clutch coil connector and the speed sensor connector.
- 4. Remove the outer tube of the speed sensor connector wire.
- 5. Remove the wire fixing cap in the rear of the speed sensor connector.
- 6. Disconnect the speed sensor connector.
- 7. Remove the shift motor.



LMAC310A

- 8. If necessary, remove the front and rear speed sensor.
- 9. Remove the mounting bolts for the rear and front case.
- 10. Make sure that the front case is facing downward so that the rear cover is facing upwards.
- 11. Separate the front case from the rear case.
- 12. Remove all traces of gasket sealant from the mating surfaces of the front case and rear case.
- 13. If the speedometer drive gear is to be replaced, first remove the flange seal or use the Impact Slide Hammer to pop off the flange seal.

Do not damage the bearing and the bearing case.

- 1. Snap ring
- 2. Bearing
- 3. Upper tone wheel
- Speedometer drive gear
 Flange seal yoke
- 5. Flarige sear yoke

LMAC310B

3

- 14. Remove the speedometer drive gear and upper tone wheel.
- 15. If the rear output shaft bearing requires replacing, remove the internal snap ring that retains the bearing in the bore.
- 16. From the outside of the case, drive out the bearing.
- 17. Remove the three nuts and washers retaining the clutch coil assembly to the rear case.
- 18.Pull the coil assembly, along with the O-rings and wire, from the case.

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Transfer System

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1. Clutch coil

Apply cam

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- 2. Clutch coil retaining nut
- 3. Wire

LMAC310C

LMAC310D

Snap ring

- 19. Remove the bearing assembly from the output shaft.
- 20. Remove the clutch housing from the output shaft.
- 21. Remove the balls and the apply cam and the waver washer from the output shaft.
- 22. Remove the snap ring from the output shaft.
- 23.Remove the clutch pack and lower tone wheel from output shaft.





LMAC310F

- 25. Remove the thrust washer from the output shaft.
- 26. Remove the oil pan magnet from the slot in the front of the case bottom.
- 27. Remove the output shaft and oil pump as an assembly.
- 28. If required, to remove the pump from the output shaft, rotate the pump to align.
- 29. Pull out the shift rail.
- 30. Remove the helical cam from the front case.
- 31. If required, remove the helical cam, torsion spring and sleeve from the shaft.



LMAC310G

- 32. Remove the high-low range shift fork and collar as an assembly.
- 33.Expand the tangs of the large snap ring in the case using the Ring Plier or equivalent.
- 34. With the input shaft against a bench, push the case down and slide the main drive gear bearing retainer off the bearing.
- 35. Lift the input shaft and front planet from the case.
- 36. If required, remove the oil seal from the case by prying and pulling on the curved-up lip of the oil seal or use the Slide Hammer to pop off theoil seal.
- 37. Remove the internal snap ring from the planetary carrier.
- 38. Separate the front planet from the input shaft.



24. Remove the chain, the driven sprocket and the drive

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Transfer Case Assembly

- 39. Remove the external snap ring from the input shaft.
- 40.Place the input shaft in a vise and remove the bearing.
- 41.Remove the thrust, thrust plate and the sun gear off the put shaft.



LMAC310H

42. Inspect the bushing and needle bearing in the end of the input shaft for wear or damage.

Under normal use, the needle bearing and bushing should not require replacement.

If replacement is required, the bushing and needle bearing must be replaced as a set.

- 43. If required, remove the front yoke to flange seal by prying and pulling on the curved-up lip of the yoke to flange seal.
- 44. If required, remove the internal snap ring retaining the front output shaft ball bearing and remove the bearing.

REASSEMBLY CASE ASSEMBLY

- If ring gear was removed for replacement, align serrations on OD of new ring gear with those in transfer case. Press in ring gear, chamferedend first. Make sure gear is not cocked and is firmly seated in case.
- 2. If removed, press two new dowel pins into case.
- 3. Press in ball bearing to bottom in transfer case and install retaining ring.
- 4. Position new oil seal and press in to seat seal flange against transfer case.



- 1. Transfer case assembly
- 2. Oil seal
- 3. Retaining ring
- 4. Ball bearing
- Dowel pin
 Ring gear
- 7. Transfer case



SHIFT CAM (ELECTRIC PARTS)

1. Insert spacer in torsion spring and install over free end of shift shaft.



- Torsion spring
 Spacer
- Shift shaft
 Electric shift cam

LMAC290C

2. Slide torsion spring and spacer on shift shaft up to drive tang and position first spring end to left (Viewed from free end of shaft) of drivetang.

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Transfer System

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2. Spacer

1. Torsion spring

Shift shaft

LMAC290D

3. Twist second spring end to right of drive tang on shift shaft.



- LMAC290E
- 4. Push torsion spring and spacer together back as far as they will go.
- 5. Slide electric shift cam onto shift shaft, drive tang on cam first.

Position drive tang on cam so that it will go under drive tang on shift shaft and between spring ends and slide cam as far as it will go.



LMAC290F

ADAPTER, INPUT SHAFT AND CARRIER

- 1. Lay planet carrier assembly on work bench with end having groove for retaining ring up.
- 2. Install sun gear with hub end up. Rotate gear of planet carrier assembly as required until sun gear is fully meshed.
- 3. Align tabs and install thrust plate into planet carrier assembly.

4. Install retaining ring (16) to complete gear carrier assembly.



LMAC280I

- 5. If removed, position needle bearing and press into input shaft to dimension shown. Press in new sleeve bearing to complete input shaft assembly.
- 6. Lift up gear carrier assembly and install input shaft assembly up through gear carrier assembly. Install thrust washer and press bearing over end of input shaft assembly. Retain bearing on input shaft with retainingring in shaft groove.
- 7. If removed, press new pin into front adapter.
- 8. Position oil seal and press into front adapter to dimension shown.
- 9. Install snap ring in groove in front adapter with long ends of snap ring in adapter groove to complete front adapter assembly.
- 10. Position front adapter assembly with face that mates with transfer case up. Support on wood blocks to provide clearance for input shaft assembly. Position assembled input shaft and carrier group over front adapter with input shaft down. Lower shaft and carrier group while expanding long ends of snapring until snap ring engages groove in outside diameter of bearing.

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Transfer Case Assembly



- 1. Sleeve bearing
- 2. Needle bearing
- Input shaft

LMAC290G

- 11.Apply continuous 1/16 in.(1.6 mm) bead of sealant (Neutral Cure RTV, Loctite 598) all around transfer case mounting facefor front, adapter. Center sealant bead between edges of face. Circle bolt holes.
- 12. Install assembled adapter, input shaft and carrier group on transfer case and attach with six bolts. Torque bolts to 20 - 34 lb·ft (27 -46 Nm)
- 13.Install breather bard and torque to 6 14 lb ft (8 19 Nm).

ديجينال تعميركارن FRONT OUTPUT SHAFT

- 1. If removed, press deflector onto yoke.
- 2. Position output shaft in transfer case and install yoke assembly, oil seal, washer and nut.
- 3. Hold yoke and torque nut to 150 180 lb·ft (203 244 Nm).



- 1. Nut 2. Washer
- 3. Oil seal
- 4. Yoke assy
- 5. Deflector
- 6. Yoke
- Output shaft(front)
 Transfer case
- . Transfer case

REDUCTION SHIFT

1. If disassembled for parts replacement, assemble reduction shift fork assembly using new pin, roller and retainer assembly.

LMAC280H

Press pin, roller and retainer assembly in to bore in reduction shift fork until retainer passes completely through and snaps in place. Make surethat cam roller turns freely.

- 2. Install two fork facings on reduction shift fork assembly.
- 3. Engage reduction shift fork assembly with reduction hub and position in transfer case, reduction hub in gear carrier assembly previously installed.
- 4. Install output shaft, engaging output shaft end with input shaft bearings and output shaft spline with reduction hub.

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Transfer System

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WD-62



- 1. Reduction hub
- 2. Shift fork facing
- 3. Reduction shift fork assy
- 4. Pin, roller and retainer assy
- 5. Retainer
- 6. Pin
- 7. Cam roller
- 8. Reduction shift fork

LMAC280G

OIL PUMP

1. Locate pump front cover. Front pump cover has tapped holes.

Position front cover so that word TOP faces down and turned so that it will be at top of transfer case when installed in vehicle. Install front pump cover over output shaft in this position.

2. Install two pump pins with spring between them in output shaft.

Flat surface on both pins must point out and face up. Center pins and spring in output shaft.

- 3. Push hose coupling onto bard on strainer and install L shaped foot on filter in slot in transfer case. Hose coupling must point in direction of pump assembly.
- 4. Install pump housing so that word REAR marked on it is up and hose bard points toward hose coupling and strainer. Lower pump housing over upper output shaft, moving pump pins inward and compressing spring so that bothpins are contained inside pump housing.
- 5. Slip hose clamp over free end of hose coupling and push onto hose bard on pump housing. Secure hose clamp over hose coupling on hose bard.
- 6. Position pump rear cover over assembly with words TOP REAR facing up and located to be at top of transfer case when installed.

Position pump retainer on cover so that tab on retainer is in notch in transfer case. Clean threads on four bolts and apply Loctite 222. Align pump holes

and install bolts. Torque bolts to 2.9 - 6.3 lb ft (4.0 -8.5 Nm) while turning outputshaft by hand to insure that pump pins movefreely.



- 7. Pump housing
- 8. Pump pin
- 9. Spring
- 10.Front pump cover
- 11.Output shaft
- 12.Strainer

CHAIN DRIVE

1. On work bench, next to transfer case assembly, position driven sprocket (with internal spline) at front output shaft endof case and drive sprocket(with smooth bore) at output shaft end.

LMAC280F

- Assemble drive chain around sprockets.
- 3. Grasp each sprocket, hold drive chain tight and parallel with transfer case, and install chain drive assembly over output shaft. It may be necessary to rotate driven sprocket slightly to engage splines on front output shaft.
- 4. Install spacer on front output shaft. Install snap ring in shaft groove over spacer.

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Transfer Case Assembly

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- 1. Snap ring
- 2. Spacer
- 3. Drive sprocket
- 4. Driven sprocket 5. Drive chain
- 6. Output shaft (rear)
- 7. Lockup collar

LMAC280E

LOCKUP SHIFT

- 1. Assemble return spring and lockup hub in lockup collar and retain with snap ring, completing 2W-4W lockup assembly.
- 2. Install rail shaft in transfer case, through reduction shift fork assembly previously installed and into blind hole in case.
- 3. Engage lockup fork in groove in 2W-4W lockup assembly and slide this group down over output shaft and rail shaft.
- 4. Install shift collar hub, engaging splines on output shaft and in 2W-4W lockup assembly.
- 5. On electric shift units only, install electric shift cam group previously assembled and clutch housing as follow :
 - 1) Position electric shift cam group rotated so that end of torsion spring will contact side of reduction shift fork assembly that faces up, towardtop of case.
 - 2) Holding rail shaft down, raise up fork assemblies slightly. Rotate electric shift cam group into position so that rolleron reduction shift fork assembly is in groove in shift cam and button on lockup fork is on cam end. Then lower this group of parts into the transfer case engaging shift shafton pin in transfer case.
 - 3) Position clutch housing in transfer case over shift collar hub. Attach with retaining ring in clutch collar hub groove.



- 2. Wiring clip 3. Identification tag
- 4. Cover assy
- 5. Magnet
- 7. Oil seal 8. Return spring 9. Rail shaft 10.Transfer case

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LMAC290J

- 1. Position cover on bed of suitable press so that open face of cover is up and parallel with press bed.
- 2. Position end of needle bearing with identification marking up and press into cover until upper end of bearing is 1.593 -1.603 in. (40.47 -40.97 mm) below face of cover that mates with transfer case.
- 3. Press in ball bearing to bottom in cover and install snap ring.
- 4. On electric shift units only, install parts as follow :
 - Verify that four O-rings (one on wire and one each on three studs) are in place on clutch coil assembly. Install clutch coil assembly in inside of cover, with electrical wire and studs extending through cover, with electrical wire and studsextending through cover. Use care not to kink or trap electrical wire under clutch coil assembly. Attach with three nutsand torque to 6 -8 lb·ft (8 - 11 Nm).
 - 2) Install motor bearing and oil seal in cover.



- 1. Oil seal
- 2. Bearing
- 3. Nut
- Clutch coil assy
- 5. Snap ring
- 6. Ball bearing
- Needle bearing
 Case cover
- LMAC290K
- 5. Install return spring over rail shaft in transfer case to rest on shift fork.
- 6. Install magnet in slot in transfer case.
- Apply continuous 1/16 in. (1.6 mm) bead of sealant (Neutral Cure RTV, Loctite 598) all around transfer case mounting face for cover assembly. Center sealant bead between edges of face. Circle bolt holes. Remove excessif sealant bead is larger than 1/16 in. (1.6 mm).



- 1. Return spring
- Rail shaft
 Output shaft
- 4. Front output shaft
- 5. Shift shaft
- 6. Dowel pin

LMAC290L

Transfer System

- 8. Install cover assembly on transfer case. All of the following alignment conditions must be met for the cover assembly to seaton transfer case properly.
 - 1) Cover holes with transfer case dowel pins.
 - 2) Cover bearings with output shafts.
 - Blind hole in cover with rail shaft. Make sure spring in not cocked. On electric shift, check with pen light through cover hole for speed sensor.
 - 4) On electric shift units, cover bearing with shift shaft.
- Install nine bolts positioning identification tag and wiring clip under bolt heads at locations. Torque bolts to 20 - 34 lb·ft (27 -46 Nm).
- 10. Install speedo gear over spline of output shaft into cover assembly.
- 11. Press new oil seal into cover assembly.

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Transfer Case Assembly



- 1. Motor assembly
- 2. Bolt
- 3. Wiring clip
- 4. Identification tag

LMAC290M

EXTERNAL ELECTRIC SHIFT

- 1. Position motor assembly so that triangular slot in motor will align with shift shaft. Move motor in to engage shift shaft and contact cover. Then rotate motor in clockwise direction until motor is in correct position andmounting holes are aligned.
- Fit O-ring on speed sensor and install speed sensor assembly in cover. Install bracket so that it is over speed sensor and install three bolts. Torque bolts to 6 - 8 lb-ft (8 - 11 Nm).
- 3. Install bolt and washer at bracket end of motor assembly and torque to 6 8 lb·ft (8 11 Nm).



- 1. Bolt
- 2. Bolt
- Speed sensor
 Motor assembly
- 5. Cover



- 1. Motor assy
- 2. Shift shaft

LMAC290O

REASSEMBLY

- 1. Before assembly, lubricate all parts with the specified grease oil.
- 2. If removed, drive the bearing into the front output case bore.
- 3. Install the internal snap ring that retains the bearing to the front case.
- If removed, install the front yoke to flange seal in the front case bore.
- 5. If removed, install the yoke to flange seal into the mounting adapter bore.



LMAC320A

- 6. If the input shaft needle bearing and bushing were removed, install a new bearing and bushing.
- 7. The recessed face of the sun gear and the snap ring groove on the bearing outer race should be toward the rear of the transfer case.
- 8. The stepped face of the thrust washer should face toward the bearing.

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Transfer System

WD-66

- 9. Slide the sun gear, thrust plate and thrust washer into position on the input shaft.
- 10. Press the bearing over the input shaft.
- 11. Install the external snap ring to the input shaft.
- 12. Install the front planet to the sun gear and input shaft.
- 13. Install the internal snap ring to the planetary carrier.



Check the installation by holding the case and carefully tapping the face of the input shaft against a wooden block to make sure the snap ringis installed.

15. Remove all traces of gasket sealant from the front case and mounting adapter mating surfaces.



LMAC320C

16. Install the high-low shift fork and high-low collar as an assembly into the front planet.

- 1. Rear output shaft
- 2. Pump body
- 3. Clamp 4. Hose
- 5. Filter

LMAC320E

19. Install the output shaft and oil pump in the input shaft. Make sure that the internal splines of the output shaft engagethe internal splines of the high-low shift collar. Make sure that the oil pump retainer arm andoil filter leg are in the groove and slot of the front case.

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Transfer Case Assembly



- 1. Oil pump
- 2. Pump retainer
- 3. Oil pump filter
- 4. Output shaft

LMAC320F

- 20.Install the oil pan magnet in the slot in the front case just above the oil filter leg.
- 21. Install the front output shaft in the front case.



LMAC320G

- 22. Install the thrust washer on the rear output shaft.
- 23.Install the chain, drive sprocket and driven sprocket as an assembly over the output shaft.

The driven sprocket (on the front output shaft) must be installed with the marking REAR facing toward the rear case, if so marked.



LMAC320H

- 24. Install tone wheel onto the front output shaft. Make sure the spline on the tone wheel engages the spline on the front output shaft.
- 25. Install clutch pack assembly onto the rear output shaft. Make sure that the spline on the clutch pack engages to the spline of the sprocket.



26. Install snap ring onto the rear output shaft. Start the snap ring over the spline and use the wave spring to seat the snap ring in the snapring groove.

If the snap ring will not install, the thrust washer inside the clutch pack may not be seated properly.



LMAC320J

- 27. Three slots on the thrust washer must be aligned with the three tabs on the clutch pack housing.
- 28. Install the apply cam onto the rear output shaft.
- 29. Install three balls into the apply cam.
- Install cam and coil housing assembly onto rear output shaft.

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Transfer System

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31. Install thrust bearing assembly onto output shaft.



LMAC320K

- 32. Install the clutch coil from inside the rear case until the wire and studs extend through the cover.
- 33. Install the washers and nuts and tighten to 8 11Nm.



3. Wire

LMAC320L

- 34. Slide the spring spacer on the cam shaft and position it beneath the drive tang.
- 35. Place the torsion spring on the cam shaft. Position the first spring tang to the left of the cam shaft drive tang.
- 37. Push the torsion spring and sleeve in as far as it will go.
- 38.Install the helical cam and slide the drive tang between the torsion spring tangs as far as it will go.



LMAC320O

39. Install the pin on the tang end of the helical cam into the hole in the front case.

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Transfer Case Assembly

Position the torsion spring tangs so that they are pointing toward the top side of the transfer case and just touching the high-low shift fork.

Do not bend the helical cam during installation to the front case be cause of possible damage to the pin at the tang end of the motor shaft.

- 40. Install the shift rail through the high-low shift fork and make sure that the reverse gear shift rail is seated in the front case bore.
- 41. Install upper and lower speed sensors into the cover. Feed the coil wire through the upper speed sensor wire shield.



42.Install upprr tone wheel, speedometer gear and rear output seal.



LMAC320Q

- 43.Coat the mating surface of the front case with sealant.
- 44. The following procedure must be followed prior to installing the rear case onto the front case half :
 - 1) Align the output shaft with the rear case output shaft bore.
 - 2) Align the helical cam with the rear case motor bore. If difficulty is encountered with seating the rear case, tap the rear output shaft with a sharp blow using a rubber mallet in a direction away fromthe triangular shaft while pushing down on the rear case.

45. Install the bolts retaining the case halves and tighten to 25 - 37 N⋅m (250 - 370 kg⋅cm, 19 25 lb⋅ft).





46. Install shift shaft oil seal if it is not installed.



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Transfer System



LMAC320S

- 47. Using pliers equipped with soft jaws, rotate the triangular shaft so it is aligned with the triangular slot in the transfer case shift motor. If triangular shaft will not rotate, rotate the rear output shaft.
- 48. Slightly loosen the two nuts that attach the slotted support bracket to the end of the motor house.
- 49. Apply the sealant to motor housing base and install on transfer case.
- 50. Install the transfer case shift motor.
- 51. Holding the slotted support bracket tight against the motor housing end secure the bracket to the transfer case, tightening the bolt with lockwasherto 8 11 N·m (80 110 kg·cm, 6 8 lb·ft).
- 52. Retighten the two nuts that attach the slotted support bracket to the end of the motor to 3-4 N⋅m (30 - 40 kg⋅m, 2 - 3 lb⋅ft).

Installation

1. Install the transfer assembly by installing the mounting bolts (8ea) from the transmission side.

MOTICE

Grease the spline end of the transmission output shaft before installing the transfer assembly.



SBLAT8001D 2. Connect the speed sensor connector (A) and 4WD connector (B).

SBLAT8003D





SBLAT8002D

4. Connect the battery (-) terminal.

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